## **Equation Solvers for Distributed Memory Computers**

by Olaf O. Storaasli, (O.O.Storaasli@larc.nasa.gov or 804-864-2927)

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A large number of scientific and engineering problems reduce to the solution of large systems of simultaneous equations. Solving large systems of simultaneous equations rapidly thus makes the solution of large-scale structures, physics, electromagnetics and fluid mechanics problems tractable. The performance of parallel computers now dwarfs traditional vector computers by nearly an order of magnitude, so the challenge is to rapidly solve large systems of equations rapidly on the new breed of scalable parallel processing supercomputers.

Research at Langley on solving equations on distributed memory computers goes back nearly ten years to the Langley Finite Element Machine, one of the nation's first parallel computers with 32 processors developed by NASA before commercial parallel computers were available. Since then, both iterative and direct parallel equation solvers have been developed and tuned for parallel computers manufactured by Flexible computer, N-Cube, Alliant, Encore, Cray, Intel, Convex and IBM. The solvers, PVSOLVE and PVS-MP are currently running on the IBM SP-1 and SP-2 under a Memorandum of Agreement with IBM which permits Langley early access to the SP-1 and SP-2 in return for IBM given permission to use the NASA solvers for advertisements, demonstrations, and trade shows. These Langley solvers are timely since in a recent \$22.4 million procurement, two IBM SP-2 supercomputers will be delivered to NASA (160 processors to NAS and 48 processors to LaRC). Based on benchmarks and the Langley parallel equation solvers, these IBM supercomputers promise to surpass the performance of traditional Cray vector supercomputers and other parallel computers.

The talk will describe the major issues involved in parallel equation solvers with particular emphasis on implementations the Intel Paragon, IBM SP-1 and SP-2.



## Equation Solvers for Distributed-Memory Computers



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### **Objective**

- Faster, cheaper, better analysis/design of large-scale structures
  - Develop algorithms to exploit distributed-memory computers
  - Evaluate computational performance



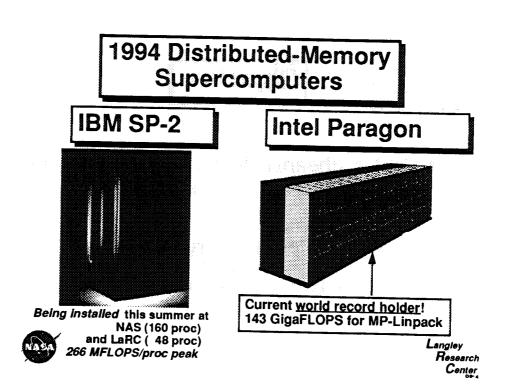


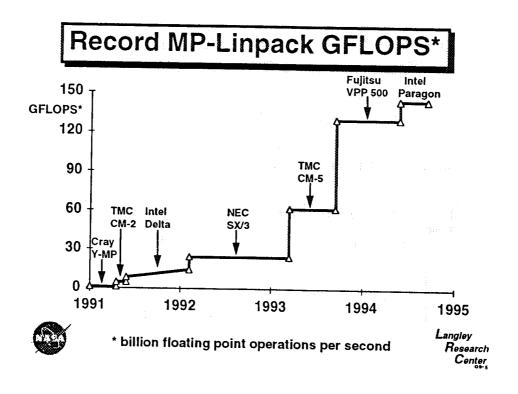
## Outline

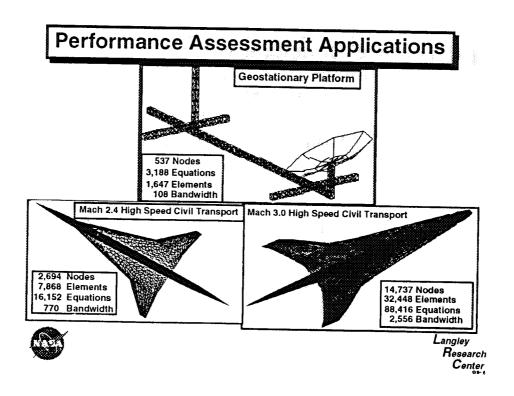


- Distributed-memory Computers
- Structural Applications
- Structural Analysis
- Nodal Generation and Assembly
- Linear Equation Solvers
- Structural Optimization
- x-Design Sensitivity

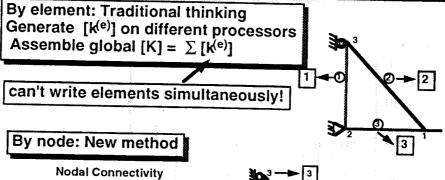






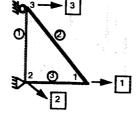


## Parallel Matrix Generation and Assembly



Node Proc. Elements





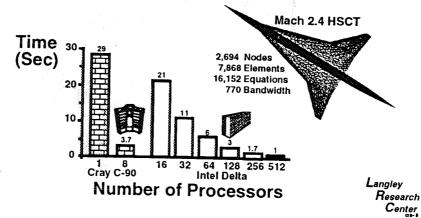
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#### Parallel Structural Matrix Generator/ Assembler Demonstrated on HSCT



 Nearly ideal parallel speedup (no interprocessor communication)







# Equation Solution Issues (Time, memory, disk space, I/O)



- Iterative or direct?
- Banded or sparse ?
- "In-core" or "out-of-core"?

#### Communication

- Broadcast or ring?
- OSF or SUNMOS?



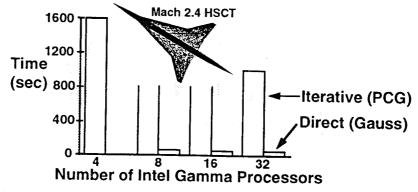
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## Iterative <u>vs</u> Direct Solvers

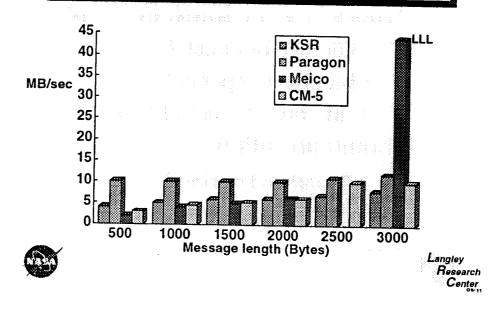


- Iterative slow, convergence not guaranteed
- Direct complex coding (banded, sparse)





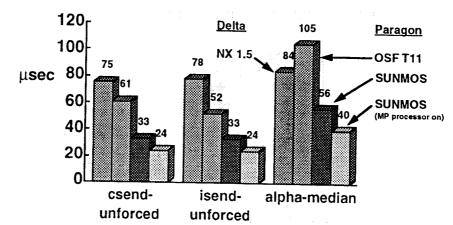
## Interprocessor Communication













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#### **Paragon Status**

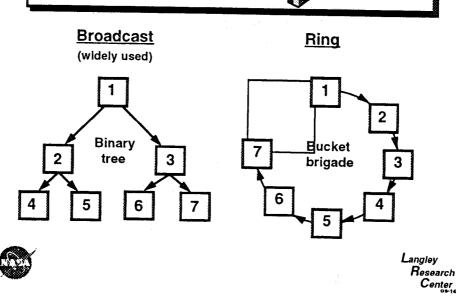


- OSF Rev 1.1 (Latency: 150 -> 85 μsec, Tools Communication: 11 -> 34 MB/sec, Memory 8 -> 6MB)
- OSF Rev 1.2 (Latency: 85 -> 50 μsec Communication: 34 -> 55 MB/sec)
- New comm chip: tested at 400 MB/sec
- Dynamic Memory: avoid inconsistencies (i.e. faster 2nd runs)
- SUNMOS: Sandia-UNM O/S (Latency: 24 μsec, Comm: 175 MB/sec, Mem: 0.3MB) 178 MB/sec on Grace (NAS benchmarks run faster)



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# Interprocessor Communication Methods

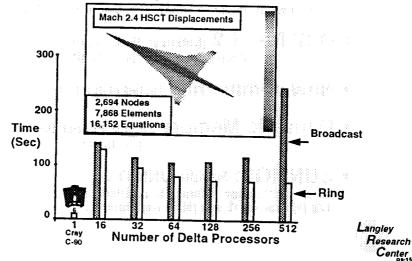




## Solution Time: Mach 2.4 HSCT



- Ring communication <u>reduced</u> solution time
- Slower than 1 Cray processor



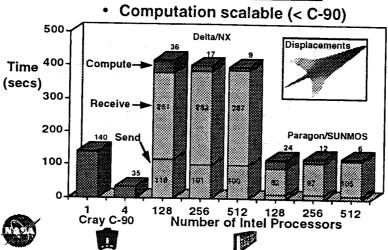


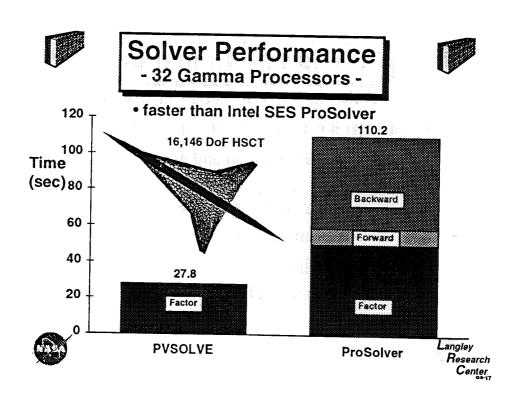


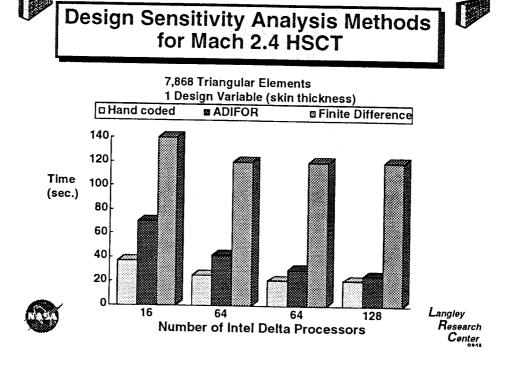
#### Solution Time Breakdown - Mach 3.0 HSCT -



- Communication dominates









### Concluding Remarks



- New algorithms for distributed-memory computers
- Perform well on large-scale applications:
- Nodal Matrix Generation and Assembly
- Equation Solvers: [K]{u} = {p} (linear, nonlinear, "out-of core", sparse)
- Structural Optimization

- Design Sensitivity

• Operate on Paragon, IBM SP-1 and SP-2!





## References

- Storsasli, O., Mguyen, D., Baddourah, M. and Qin, J.; Computational Mechanics Analysis Tools for Parallel-Vector Supercomputers", AIAA/ASME/ASCE/AHS/ASC 34th Structures, Structural Dynamics and Materials Conference Proceedings, Part 2, pp. 772-778, April 1993.
- also International Journal of Computing Systems in Engineering, Vol. 4, No. 2-4, 1993 pp. 349-354
- on MOSAIC-WWW (Langley Technical Report Server)
- Questions: O.O.Storaasli@larc.nasa.gov
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#### SESSION 5 Automatic Differentiation

Chaired by

Olaf Storaasli

- 5.1 Applications of Automatic Differentiation in Computational Fluid Dynamics Larry Green
- 5.2 Automatic Differentiation for Design Sensitivity Analysis of Structural Systems Using Multiple Processors Duc Nguyen, Olaf Storaasli, Jiangning Qin and Ramzi Qamar